



## Megasquirt-3 and Megasquirt-2 CAN realtime data broadcasting format

*CAN broadcasting is supported in:*

- *Megasquirt-3 firmware MS3 1.4.x only. Not supported in earlier firmwares.*
- *Megasquirt-2 firmware MS2/Extra 3.4.x only. Not supported in earlier firmwares.*

11bit CAN headers used, sequential addressing. All data is big-endian.

User can select base identifier. Default is 1520 decimal. Each subsequent 'Group' of data is transmitted at the base identifier + group number. i.e. 'group 17' is transmitted at base identifier + 17.

User can enable/disable groups of 8 bytes of data. Offsets do not change.

For dashes treating the data as one single message, the 'Group' and 'Offset in group' columns can be ignored.

For dashes handling each message discretely, ignore the total offset column.

See also Megasquirt reference manuals for more detailed description of the data fields (channels.)

Note that the offsets here are specific to the CAN broadcast method and do not align with serial data, they are grouped here for more logical selection by the user.

*Updated as of 2014-03-10 for MS3 pre-1.4 alpha1 and MS2/Extra pre-3.4 alpha1.*

Please report any errors or omissions to [contact@megasquirt.co.uk](mailto:contact@megasquirt.co.uk)

Group	Offset in group	Total offset	Size	Sign?	Name	Function	Units	Multiply	Divide	Add	MS2?
0	0	0	2	-	seconds	Seconds ECU has been on	s	1	1	0	Y
0	2	2	2	-	pw1	Main pulsewidth bank 1	ms	1	1000	0	Y
0	4	4	2	-	pw2	Main pulsewidth bank 2	ms	1	1000	0	Y
0	6	6	2	-	rpm	Engine RPM	RPM	1	1	0	Y
1	0	8	2	Y	adv_deg	Final ignition spark advance	deg BTDC	1	10	0	Y
1	2	10	1	-	squirt	Bitfield of batch fire injector events	-	1	1	0	Y
1	3	11	1	-	engine	Bitfield of engine status	-	1	1	0	Y
1	4	12	1	-	afrtgt1	Bank 1 AFR target	AFR	1	10	0	Y
1	5	13	1	-	afrtgt2	Bank 2 AFR target	AFR	1	10	0	Y
1	6	14	1	-	wbo2_en1	not used	-	1	1	0	Y
1	7	15	1	-	wbo2_en2	not used	-	1	1	0	Y
2	0	16	2	Y	baro	Barometric pressure	kPa	1	10	0	Y
2	2	18	2	Y	map	Manifold air pressure	kPa	1	10	0	Y
2	4	20	2	Y	mat	Manifold air temperature	deg F	1	10	0	Y
2	6	22	2	Y	clt	Coolant temperature	deg F	1	10	0	Y
3	0	24	2	Y	tps	Throttle position	%	1	10	0	Y
3	2	26	2	Y	batt	Battery voltage	V	1	10	0	Y
3	4	28	2	Y	afr1_old	AFR1 (Deprecated on MS3)	AFR	1	10	0	Y
3	6	30	2	Y	afr2_old	AFR2 (Deprecated on MS3)	AFR	1	10	0	Y
4	0	32	2	Y	knock	Indication of knock input	%	1	10	0	Y
4	2	34	2	Y	egocor1	EGO bank 1 correction	%	1	10	0	Y
4	4	36	2	Y	egocor2	EGO bank2 correction	%	1	10	0	Y

4	6	38	2	Y	aircor	Air density correction	%	1	10	0	Y
5	0	40	2	Y	warmcor	Warmup correction	%	1	10	0	Y
5	2	42	2	Y	tpsaccl	TPS-based acceleration	%	1	10	0	Y
5	4	44	2	Y	tpsfuelcut	TPS-based fuel cut	%	1	10	0	Y
5	6	46	2	Y	barocor	Barometric fuel correction	%	1	10	0	Y
6	0	48	2	Y	totalcor	Total fuel correction	%	1	10	0	Y
6	2	50	2	Y	ve1	VE value table/bank 1	%	1	10	0	Y
6	4	52	2	Y	ve2	VE value table/bank 2	%	1	10	0	Y
6	6	54	2	Y	iacstep	Stepper idle step number or PWM idle value duty	step duty%	1 392	1 1000	0 0	Y
7	0	56	2	Y	cold_adv_deg	Cold advance	deg	1	10	0	Y
7	2	58	2	Y	TPSdot	Rate of change of TPS	%/s	1	10	0	Y
7	4	60	2	Y	MAPdot	Rate of change of MAP	kPa/s	1	1	0	Y
7	6	62	2	Y	RPMdot	Rate of change of RPM	RPM/s	10	1	0	Y
8	0	64	2	Y	MAFload	Synthetic 'load' from MAF	%	1	10	0	Y
8	2	66	2	Y	fuelload	'Load' used for fuel table lookup e.g. equals MAP in Speed-Density	%	1	10	0	Y
8	4	68	2	Y	fuelcor	Adjustment to fuel from Flex	%	1	10	0	Y
8	6	70	2	Y	MAF	Mass Air Flow (Scaling depend on range, 650g/s shown)	g/s	1	100	0	Y
9	0	72	2	Y	egoV1	Voltage from O2#1 (Deprecated on MS3)	V	1	100	0	Y
9	2	74	2	Y	egoV2	Voltage from O2#2 (Deprecated on MS3)	V	1	100	0	Y
9	4	76	2	-	dwell	Main ignition dwell	ms	1	10	0	Y
9	6	78	2	-	dwell_trl	Trailing ignition dwell	ms	1	10	0	Y
10	0	80	1	-	status1	ECU status bitfield	-	1	1	0	Y
10	1	81	1	-	status2	ECU status bitfield	-	1	1	0	Y
10	2	82	1	-	status3	ECU status bitfield	-	1	1	0	Y

10	3	83	1	-	status4	Not typically used	-	1	1	0	Y
10	4	84	2	Y	status5	Not typically used	-	1	1	0	Y
10	6	86	1	-	status6	ECU status bitfield	-	1	1	0	-
10	7	87	1	-	status7	ECU status bitfield	-	1	1	0	-
11	0	88	2	Y	fuelload2	'Load' used for fuelling on modified table	%	1	10	0	Y
11	2	90	2	Y	ignload	'Load' used for ignition table lookup	%	1	10	0	Y
11	4	92	2	Y	ignload2	'Load' used for modifier ignition table lookup	%	1	10	0	Y
11	6	94	2	Y	airtemp	Estimated intake air temperature	deg F	1	10	0	Y
12	0	96	4	Y	wallfuel1	Calculated volume of fuel on intake walls from EAE (in injector pulsewidth units)	us	1	100	0	Y
12	4	100	4	Y	wallfuel2	Second channel of same	us	1	100	0	Y
13	0	104	2	Y	sensors1	Generic sensor input 1 (gpioadc0 on MS2)	-	1	10	0	Y
13	2	106	2	Y	sensors2	Generic sensor input 2 (gpioadc1 on MS2)	-	1	10	0	Y
13	4	108	2	Y	sensors3	Generic sensor input 3 (gpioadc2 on MS2)	-	1	10	0	Y
13	6	110	2	Y	sensors4	Generic sensor input 4 (gpioadc3 on MS2)	-	1	10	0	Y
14	0	112	2	Y	sensors5	Generic sensor input 5 (gpioadc4 on MS2)	-	1	10	0	Y
14	2	114	2	Y	sensors6	Generic sensor input 6 (gpioadc5 on MS2)	-	1	10	0	Y
14	4	116	2	Y	sensors7	Generic sensor input 7 (gpioadc6 on MS2)	-	1	10	0	Y
14	6	118	2	Y	sensors8	Generic sensor input 8 (gpioadc7 on MS2)	-	1	10	0	Y
15	0	120	2	Y	sensors9	Generic sensor input 9 (adc6 on MS2)	-	1	10	0	Y
15	2	122	2	Y	sensors10	Generic sensor input 10 (adc7 on MS2)	-	1	10	0	Y
15	4	124	2	Y	sensors11	Generic sensor input 11	-	1	10	0	-
15	6	126	2	Y	sensors12	Generic sensor input 12	-	1	10	0	-
16	0	128	2	Y	sensors13	Generic sensor input 13	-	1	10	0	-
16	2	130	2	Y	sensors14	Generic sensor input 14	-	1	10	0	-
16	4	132	2	Y	sensors15	Generic sensor input 15	-	1	10	0	-

16	6	134	2	Y	sensors16	Generic sensor input 16	-	1	10	0	-
17	0	136	2	Y	boost_targ_1	Target boost - channel 1	kPa	1	10	0	Y
17	2	138	2	Y	boost_targ_2	Target boost - channel 2	kPa	1	10	0	-
17	4	140	1	-	boostduty	Duty cycle on boost solenoid 1	%	1	1	0	Y
17	5	141	1	-	boostduty2	Duty cycle on boost solenoid 2	%	1	1	0	-
17	6	142	2	Y	maf_volts	MAF voltage (synthesised for frequency MAFs)	V	1	1000	0	Y
18	0	144	2	Y	pwseq1	Sequential Pulsewidth for cyl#1	ms	1	1000	0	Y
18	2	146	2	Y	pwseq2	Sequential Pulsewidth for cyl#2	ms	1	1000	0	Y
18	4	148	2	Y	pwseq3	Sequential Pulsewidth for cyl#3	ms	1	1000	0	Y
18	6	150	2	Y	pwseq4	Sequential Pulsewidth for cyl#4	ms	1	1000	0	Y
19	0	152	2	Y	pwseq5	Sequential Pulsewidth for cyl#5	ms	1	1000	0	-
19	2	154	2	Y	pwseq6	Sequential Pulsewidth for cyl#6	ms	1	1000	0	-
19	4	156	2	Y	pwseq7	Sequential Pulsewidth for cyl#7	ms	1	1000	0	-
19	6	158	2	Y	pwseq8	Sequential Pulsewidth for cyl#8	ms	1	1000	0	-
20	0	160	2	Y	pwseq9	Sequential Pulsewidth for cyl#9	ms	1	1000	0	-
20	2	162	2	Y	pwseq10	Sequential Pulsewidth for cyl#10	ms	1	1000	0	-
20	4	164	2	Y	pwseq11	Sequential Pulsewidth for cyl#11	ms	1	1000	0	-
20	6	166	2	Y	pwseq12	Sequential Pulsewidth for cyl#12	ms	1	1000	0	-
21	0	168	2	Y	pwseq13	Sequential Pulsewidth for cyl#13	ms	1	1000	0	-
21	2	170	2	Y	pwseq14	Sequential Pulsewidth for cyl#14	ms	1	1000	0	-
21	4	172	2	Y	pwseq15	Sequential Pulsewidth for cyl#15	ms	1	1000	0	-
21	6	174	2	Y	pwseq16	Sequential Pulsewidth for cyl#16	ms	1	1000	0	-
22	0	176	2	Y	egt1	EGT 1	deg F	1	10	0	-
22	2	178	2	Y	egt2	EGT 2	deg F	1	10	0	-
22	4	180	2	Y	egt3	EGT 3	deg F	1	10	0	-

22	6	182	2	Y	egt4	EGT 4	deg F	1	10	0	-
23	0	184	2	Y	egt5	EGT 5	deg F	1	10	0	-
23	2	186	2	Y	egt6	EGT 6	deg F	1	10	0	-
23	4	188	2	Y	egt7	EGT 7	deg F	1	10	0	-
23	6	190	2	Y	egt8	EGT 8	deg F	1	10	0	-
24	0	192	2	Y	egt9	EGT 9	deg F	1	10	0	-
24	2	194	2	Y	egt10	EGT 10	deg F	1	10	0	-
24	4	196	2	Y	egt11	EGT 11	deg F	1	10	0	-
24	6	198	2	Y	egt12	EGT 12	deg F	1	10	0	-
25	0	200	2	Y	egt13	EGT 13	deg F	1	10	0	-
25	2	202	2	Y	egt14	EGT 14	deg F	1	10	0	-
25	4	204	2	Y	egt15	EGT 15	deg F	1	10	0	-
25	6	206	2	Y	egt16	EGT 16	deg F	1	10	0	-
26	0	208	1	-	nitrous1_duty	Duty cycle to nitrous solenoid 1	%	1	1	0	-
26	1	209	1	-	nitrous2_duty	Duty cycle to nitrous solenoid 2	%	1	1	0	-
26	2	210	2	-	nitrous_timer_out	Timer used internally for nitrous system	s	1	1000	0	-
26	4	212	2	Y	n2o_addfuel	Fuel pulsewidth added due to nitrous system	ms	1	1000	0	Y
26	6	214	2	Y	n2o_retard	Timing retard due to nitrous system	deg	1	10	0	Y
27	0	216	2	Y	canpwwmin1	PWM period from remote board	-	1	1	0	Y
27	2	218	2	Y	canpwwmin2	PWM period from remote board	-	1	1	0	Y
27	4	220	2	Y	canpwwmin3	PWM period from remote board	-	1	1	0	Y
27	6	222	2	Y	canpwwmin4	PWM period from remote board	-	1	1	0	Y
28	0	224	2	-	cl_idle_targ_rpm	Closed-loop idle target RPM	RPM	1	1	0	Y
28	2	226	2	Y	tpsadc	ADC count from TPS	-	1	1	0	Y
28	4	228	2	Y	eaeload	'Load' used for EAE calc	%	1	10	0	Y

28	6	230	2	Y	afrload	'Load' used for AFR table lookups	%	1	10	0	Y
29	0	232	2	-	EAEfcor1	Fuel correction from EAE - channel 1	%	1	10	0	Y
29	2	234	2	-	EAEfcor2	Fuel correction from EAE - channel 2	%	1	10	0	Y
29	4	236	2	Y	VSS1dot	Rate of change of VSS1	ms-2	1	10	0	-
29	6	238	2	Y	VSS2dot	Rate of change of VSS2	ms-2	1	10	0	-
30	0	240	2	Y	accelx	External accelerometer X	ms-2	1	1000	0	-
30	2	242	2	Y	accely	External accelerometer Y	ms-2	1	1000	0	-
30	4	244	2	Y	accelz	External accelerometer Z	ms-2	1	1000	0	-
30	6	246	1	-	stream_level	Volume level on audio input	-	1	1	0	-
30	7	247	1	-	water_duty	Duty cycle to water injection solenoid	%	1	1	0	-
31	0	248	1	-	AFR1	AFR cyl#1	AFR	1	10	0	-
31	1	249	1	-	AFR2	AFR cyl#2	AFR	1	10	0	-
31	2	250	1	-	AFR3	AFR cyl#3	AFR	1	10	0	-
31	3	251	1	-	AFR4	AFR cyl#4	AFR	1	10	0	-
31	4	252	1	-	AFR5	AFR cyl#5	AFR	1	10	0	-
31	5	253	1	-	AFR6	AFR cyl#6	AFR	1	10	0	-
31	6	254	1	-	AFR7	AFR cyl#7	AFR	1	10	0	-
31	7	255	1	-	AFR8	AFR cyl#8	AFR	1	10	0	-
32	0	256	1	-	AFR9	AFR cyl#9	AFR	1	10	0	-
32	1	257	1	-	AFR10	AFR cyl#10	AFR	1	10	0	-
32	2	258	1	-	AFR11	AFR cyl#11	AFR	1	10	0	-
32	3	259	1	-	AFR12	AFR cyl#12	AFR	1	10	0	-
32	4	260	1	-	AFR13	AFR cyl#13	AFR	1	10	0	-
32	5	261	1	-	AFR14	AFR cyl#14	AFR	1	10	0	-
32	6	262	1	-	AFR15	AFR cyl#15	AFR	1	10	0	-
32	7	263	1	-	AFR16	AFR cyl#16	AFR	1	10	0	-

33	0	264	1	-	duty_pwm 1	Generic PWM duty 1	%	1	1	0	-
33	1	265	1	-	duty_pwm 2	Generic PWM duty 2	%	1	1	0	-
33	2	266	1	-	duty_pwm 3	Generic PWM duty 3	%	1	1	0	-
33	3	267	1	-	duty_pwm 4	Generic PWM duty 4	%	1	1	0	-
33	4	268	1	-	duty_pwm 5	Generic PWM duty 5	%	1	1	0	-
33	5	269	1	-	duty_pwm 6	Generic PWM duty 6	%	1	1	0	-
33	6	270	1	Y	gear	Current gear selected	-	1	1	0	-
33	7	271	1	-	status8	Engine status bitfield	-	1	1	0	-
34	0	272	2	Y	EGOV1	Voltage from O2 cyl#1	V	489	100000	0	-
34	2	274	2	Y	EGOV2	Voltage from O2 cyl#2	V	489	100000	0	-
34	4	276	2	Y	EGOV3	Voltage from O2 cyl#3	V	489	100000	0	-
34	6	278	2	Y	EGOV4	Voltage from O2 cyl#4	V	489	100000	0	-
35	0	280	2	Y	EGOV5	Voltage from O2 cyl#5	V	489	100000	0	-
35	2	282	2	Y	EGOV6	Voltage from O2 cyl#6	V	489	100000	0	-
35	4	284	2	Y	EGOV7	Voltage from O2 cyl#7	V	489	100000	0	-
35	6	286	2	Y	EGOV8	Voltage from O2 cyl#8	V	489	100000	0	-
36	0	288	2	Y	EGOV9	Voltage from O2 cyl#9	V	489	100000	0	-
36	2	290	2	Y	EGOV10	Voltage from O2 cyl#10	V	489	100000	0	-
36	4	292	2	Y	EGOV11	Voltage from O2 cyl#11	V	489	100000	0	-
36	6	294	2	Y	EGOV12	Voltage from O2 cyl#12	V	489	100000	0	-
37	0	296	2	Y	EGOV13	Voltage from O2 cyl#13	V	489	100000	0	-
37	2	298	2	Y	EGOV14	Voltage from O2 cyl#14	V	489	100000	0	-
37	4	300	2	Y	EGOV15	Voltage from O2 cyl#15	V	489	100000	0	-
37	6	302	2	Y	EGOV16	Voltage from O2 cyl#16	V	489	100000	0	-
38	0	304	2	Y	EGOCOR1	EGO correction cyl#1	%	1	10	0	-
38	2	306	2	Y	EGOCOR2	EGO correction cyl#2	%	1	10	0	-

38	4	308	2	Y	EGOcor3	EGO correction cyl#3	%	1	10	0	-
38	6	310	2	Y	EGOcor4	EGO correction cyl#4	%	1	10	0	-
39	0	312	2	Y	EGOcor5	EGO correction cyl#5	%	1	10	0	-
39	2	314	2	Y	EGOcor6	EGO correction cyl#6	%	1	10	0	-
39	4	316	2	Y	EGOcor7	EGO correction cyl#7	%	1	10	0	-
39	6	318	2	Y	EGOcor8	EGO correction cyl#8	%	1	10	0	-
40	0	320	2	Y	EGOcor9	EGO correction cyl#9	%	1	10	0	-
40	2	322	2	Y	EGOcor10	EGO correction cyl#10	%	1	10	0	-
40	4	324	2	Y	EGOcor11	EGO correction cyl#11	%	1	10	0	-
40	6	326	2	Y	EGOcor12	EGO correction cyl#12	%	1	10	0	-
41	0	328	2	Y	EGOcor13	EGO correction cyl#13	%	1	10	0	-
41	2	330	2	Y	EGOcor14	EGO correction cyl#14	%	1	10	0	-
41	4	332	2	Y	EGOcor15	EGO correction cyl#15	%	1	10	0	-
41	6	334	2	Y	EGOcor16	EGO correction cyl#16	%	1	10	0	-
42	0	336	2	-	VSS1	Vehicle Speed 1	ms-1	1	10	0	-
42	2	338	2	-	VSS2	Vehicle Speed 2	ms-1	1	10	0	-
42	4	340	2	-	VSS3	Vehicle Speed 3	ms-1	1	10	0	-
42	6	342	2	-	VSS4	Vehicle Speed 4	ms-1	1	10	0	-
43	0	344	1	-	synccnt	Sync-loss counter	-	1	1	0	Y
43	1	345	1	-	syncreason	Sync-loss reason code	-	1	1	0	Y
43	2	346	2	-	sd_filenum	SDcard file number	-	1	1	0	-
43	4	348	1	-	sd_error	SDcard error number	-	1	1	0	-
43	5	349	1	-	sd_phase	SDcard internal code	-	1	1	0	-
43	6	350	1	-	sd_status	SDcard status bitfield	-	1	1	0	-
43	7	351	1	-	timing_err	Calculated error in ignition timing	%	1	1	0	Y
44	0	352	2	Y	vvt_ang1	VVT actual angle 1	deg	1	10	0	-

44	2	354	2	Y	vvt_ang2	VVT actual angle 2	deg	1	10	0	-
44	4	356	2	Y	vvt_ang3	VVT actual angle 3	deg	1	10	0	-
44	6	358	2	Y	vvt_ang4	VVT actual angle 4	deg	1	10	0	-
45	0	360	2	Y	vvt_target1	VVT target angle 1	deg	1	10	0	-
45	2	362	2	Y	vvt_target2	VVT target angle 2	deg	1	10	0	-
45	4	364	2	Y	vvt_target3	VVT target angle 3	deg	1	10	0	-
45	6	366	2	Y	vvt_target4	VVT target angle 4	deg	1	10	0	-
46	0	368	1	-	vvt_duty1	VVT solenoid 1 duty cycle	%	392	1000	0	-
46	1	369	1	-	vvt_duty2	VVT solenoid 2 duty cycle	%	392	1000	0	-
46	2	370	1	-	vvt_duty3	VVT solenoid 3 duty cycle	%	392	1000	0	-
46	3	371	1	-	vvt_duty4	VVT solenoid 4 duty cycle	%	392	1000	0	-
46	4	372	2	Y	inj_timing_pri	Injection Timing Angle (primary)	deg BTDC	1	10	0	Y
46	6	374	2	Y	inj_timing_sec	Injection Timing Angle (secondary)	deg BTDC	1	10	0	Y
47	0	376	2	Y	fuel_pct	Ethanol content of fuel for Flex sensor	%	1	10	0	Y
47	2	378	2	Y	tps_accel	TPSdot based accel	%	1	10	0	-
47	4	380	2	-	SS1	Shaft speed 1	RPM	10	1	0	-
47	6	382	2	-	SS2	Shaft speed 2	RPM	10	1	0	-
48	0	384	1	-	knock_cyl1	Knock % cyl #1	%	4	10	0	-
48	1	385	1	-	knock_cyl2	Knock % cyl #2	%	4	10	0	-
48	2	386	1	-	knock_cyl3	Knock % cyl #3	%	4	10	0	-
48	3	387	1	-	knock_cyl4	Knock % cyl #4	%	4	10	0	-
48	4	388	1	-	knock_cyl5	Knock % cyl #5	%	4	10	0	-
48	5	389	1	-	knock_cyl6	Knock % cyl #6	%	4	10	0	-
48	6	390	1	-	knock_cyl7	Knock % cyl #7	%	4	10	0	-
48	7	391	1	-	knock_cyl8	Knock % cyl #8	%	4	10	0	-
49	0	392	1	-	knock_cyl9	Knock % cyl #9	%	4	10	0	-

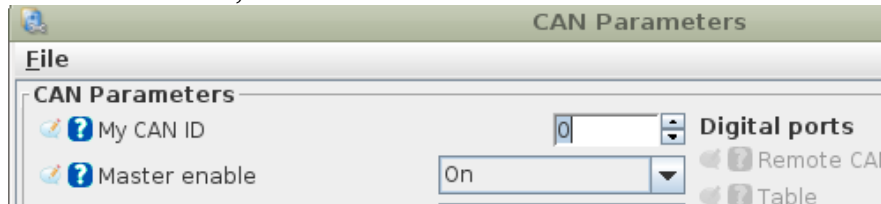
49	1	393	1	-	knock_cyl10	Knock % cyl #10	%	4	10	0	-
49	2	394	1	-	knock_cyl11	Knock % cyl #11	%	4	10	0	-
49	3	395	1	-	knock_cyl12	Knock % cyl #12	%	4	10	0	-
49	4	396	1	-	knock_cyl13	Knock % cyl #13	%	4	10	0	-
49	5	397	1	-	knock_cyl14	Knock % cyl #14	%	4	10	0	-
49	6	398	1	-	knock_cyl15	Knock % cyl #15	%	4	10	0	-
49	7	399	1	-	knock_cyl16	Knock % cyl #16	%	4	10	0	-
50	0	400	2	Y	map_accel	MAPdot based accel	%	1	10	0	-
50	2	402	2	Y	total_accel	Total accel	%	1	10	0	-
50	5	404	2	-	launch_timer	Timer for timed-launch retard	s	1	1000	0	-
50	6	406	2	Y	launch_retard	Launch retard	deg	1	10	0	-
51	0	408	1	-	porta	CPU portA bitfield	-	1	1	0	Y
51	1	409	1	-	portb	CPU portB bitfield	-	1	1	0	Y
51	2	410	1	-	porteh	CPU portE/portH bitfield	-	1	1	0	Y
51	3	411	1	-	portk	CPU portK bitfield	-	1	1	0	-
51	4	412	1	-	portmj	CPU portM/portJ bitfield	-	1	1	0	Y
51	5	413	1	-	portp	CPU portP bitfield	-	1	1	0	-
51	6	414	1	-	portt	CPU portT bitfield	-	1	1	0	Y
51	7	415	1	-	cel_errorcode	CEL error code	-	1	1	0	-
52	0	416	1	-	canin1	CAN input 1 bitfield (CAN port 1 on MS2)	-	1	1	0	Y
52	1	417	1	-	canin2	CAN input 1 bitfield (CAN port 2 on MS2)	-	1	1	0	Y
52	2	418	1	-	canout	CAN output 1 bitfield (CAN port 3 on MS2)	-	1	1	0	Y
52	3	419	1	-	knk_rtd	Knock retard	deg	1	10	0	Y
52	4	420	2	Y	fuelflow	Average fuel flow	cc/min	1	1	0	-
52	6	422	2	Y	fuelcons	Average fuel consumption	l/km	1	1	0	-
53	0	424	2	Y	fuel_press1	Fuel pressure 1	kPa	1	10	0	-

53	2	426	2	Y	fuel_press2	Fuel pressure 2	kPa	1	10	0	-
53	4	428	2	Y	fuel_temp1	Fuel temperature 1	deg F	1	10	0	-
53	6	430	2	Y	fuel_temp2	Fuel temperature 1	deg F	1	10	0	-
54	0	432	2	Y	batt_cur	Battery current (alternator system)	A	1	10	0	-
54	2	434	2	-	cel_status	CEL status bitfield	-	1	1	0	-
54	4	436	1	-	fp_duty	Fuel pump output duty	%	392	1000	0	-
54	5	437	1	-	alt_duty	Alternator field output duty	%	1	1	0	-
54	6	438	1	-	load_duty	Alternator measured load-sense duty	%	1	1	0	-
54	7	439	1	-	alt_targv	Alternator target voltage	V	1	10	0	-
55	0	440	2	-	looptime	Main code loop execution time	us	1	1	0	Y
55	2	442	2	-	fueltemp_cor	Fuel temperature correction	%	1	10	0	-
55	4	444	2	-	fuelpress_cor	Fuel pressure correction	%	1	10	0	-
55	6	446	1	Y	ltt_cor	Long term trim correction	%	1	10	0	-
55	7	447	1	-	sp1	Unused	-				-
56	0	448	2	Y	tc_retard	Traction control retard	deg	1	10	0	-
56	2	450	2	Y	cel_retard	CEL retard	deg	1	10	0	-
56	4	452	2	Y	fc_retard	Fuel-cut (overrun) retard	deg	1	10	0	-
56	6	454	2	Y	als_addfuel	ALS added fuel	deg	1	10	0	-
57	0	456	2	Y	base_advance	Base timing from tables	deg	1	10	0	Y
57	2	458	2	Y	idle_cor_advance	Idle correction advance	deg	1	10	0	Y
57	4	460	2	Y	mat_retard	MAT retard	deg	1	10	0	Y
57	6	462	2	Y	flex_advance	Flex advance	deg	1	10	0	Y
58	0	464	2	Y	adv1	Timing lookup from table 1	deg	1	10	0	Y
58	2	466	2	Y	adv2	Timing lookup from table 2	deg	1	10	0	Y
58	4	468	2	Y	adv3	Timing lookup from table 3	deg	1	10	0	Y
58	6	470	2	Y	adv4	Timing lookup from table 4	deg	1	10	0	-

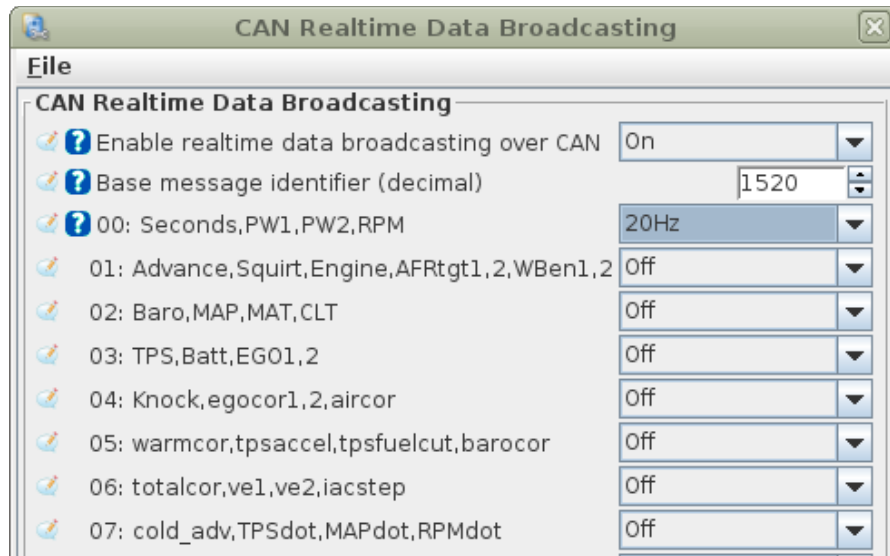
59	0	472	2	Y	revlim_retard	Revlimiter 'soft' retard	deg	1	10	0	Y
59	2	474	2	Y	als_timing	ALS timing change	deg	1	10	0	-
59	4	476	2	Y	ext_advance	External advance (e.g. trans)	deg	1	10	0	Y
59	6	478	2	Y	deadtime1	Injector deadtime in use (#1)	deg	1	10	0	Y
60	0	480	2	Y	launch_timing	Launch control timing	deg	1	10	0	-
60	2	482	2	Y	step3_timing	3-step timing	deg	1	10	0	-
60	4	484	2	Y	vsslaunch_retard	Wheel-speed based launch retard	deg	1	10	0	-
60	6	486	2	-	cel_status2	CEL status 2	deg	1	10	0	-
61	0	488	1	Y	gps_latdeg	External GPS latitude deg	deg	1	1	0	-
61	1	489	1	-	gps_latmin	GPS latitude minutes	min	1	1	0	-
61	2	490	2	-	gps_latmmin	GPS latitude milli-minutes	mmin	1	1	0	-
61	4	492	1	-	gps_londeg	GPS longitude degree	deg	1	1	0	-
61	5	493	1	-	gps_lonmin	GPS longitude minute	min	1	1	0	-
61	6	494	2	-	gps_lonmmin	GPS longitude milli-minutes	mmin	1	1	0	-
62	0	496	1	-	gps_outstatus	GPS status byte (bit 0 = N/S)	-	1	1	0	-
62	1	497	1	Y	gps_altk	GPS altitude km	km	1	1	0	-
62	2	498	2	-	gps_altm	GPS altitude m	m	1	1	0	-
62	4	500	2	-	gps_speed	GPS speed	ms-1	1	10	0	-
62	6	502	2	-	gps_course	GPS course	deg	1	10	0	-
63	0	504	1	-	generic_pid_duty 1	Generic closed-loop duty 1	%	392	1000	0	-
63	1	505	1	-	generic_pid_duty 2	Generic closed-loop duty 2	%	392	1000	0	-
63	2	506	6	-	-	Unused	-	-	-	-	-

## User configuration in Megasquirt-3, MS3-Pro, MS3-Gold and other MS3 based ECUs

To use this feature, the user needs to enable the CAN master enable:



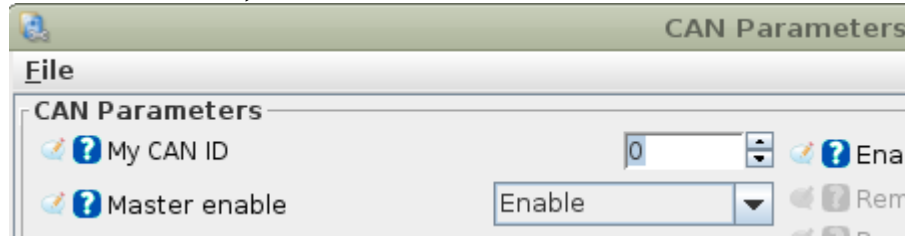
enable CAN realtime data broadcasting



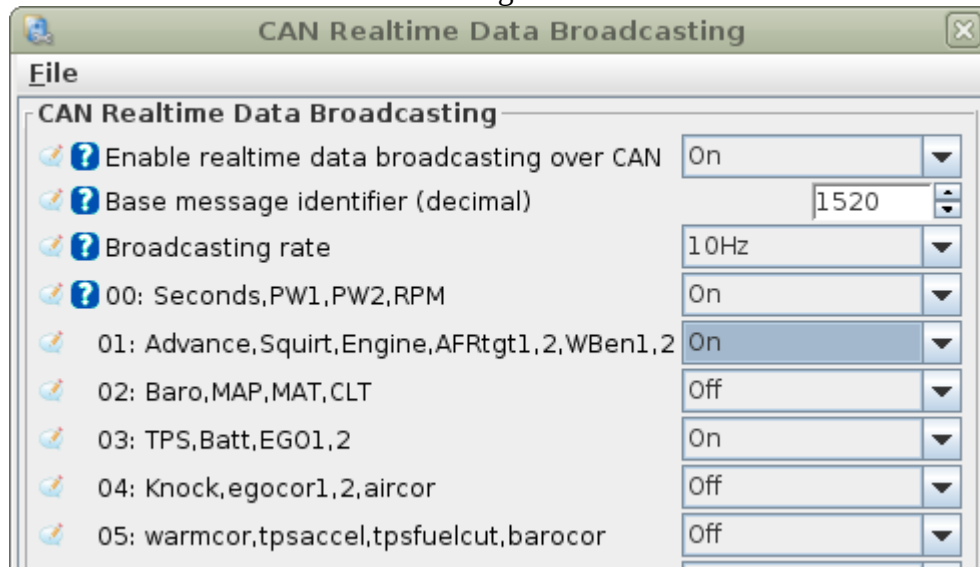
For each group of channels required, the broadcast frequency should be set.

## User configuration in Megasquirt-2, Microsquirt and other MS2 based ECUs

To use this feature, the user needs to enable the CAN master enable:



enable CAN realtime data broadcasting



The broadcast frequency should be set and the required groups of channels enabled.